# Assignment - 4

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| **Assignment Date** | **17 October 2022** |
| **Student Name** | **Mohamed anas.m** |
| **Student Roll Number** | **49621911009** |
| **Maximum Marks** | **2 Marks** |

# Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distanceis less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

# CODE 1 :

#include <WiFi.h> #include <PubSubClient.h>

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength);

//-------credentials of IBM Accounts------

#define ORG "deb9ji"//IBM ORGANITION ID

#define DEVICE\_TYPE "IOT\_FIRE"//Device type mentioned in ibm watson IOT Platform #define DEVICE\_ID "792001"//Device ID mentioned in ibm watson IOT Platform #define TOKEN "1911009abcdefgh" //Token

String data3;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char publishTopic[] = "iot-2/evt/Data/fmt/json";

char subscribetopic[] = "iot-2/cmd/test/fmt/String"; char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;

WiFiClient wifiClient;

PubSubClient client(server, 1883, callback ,wifiClient); const int trigPin = 5;

const int echoPin = 18;

#define SOUND\_SPEED 0.034 long duration;

float distance; void setup() {

**Serial**.begin(115200); pinMode(trigPin, OUTPUT); pinMode(echoPin, INPUT); wificonnect(); mqttconnect();

}

void loop()

{

digitalWrite(trigPin, LOW); delayMicroseconds(2); digitalWrite(trigPin, HIGH); delayMicroseconds(10); digitalWrite(trigPin, LOW); duration = pulseIn(echoPin, HIGH);

distance = duration \* SOUND\_SPEED/2;

**Serial**.print("Distance (cm): "); **Serial**.println(distance); if(distance<100)

{

**Serial**.println("ALERT!!"); delay(1000); PublishData(distance); delay(1000);

if (!client.loop()) { mqttconnect();

}

}

delay(1000);

}

void PublishData(float dist) { mqttconnect();

String payload = "{\"Distance\":"; payload += dist;

payload += ",\"ALERT!!\":""\"Distance less than 100cms\""; payload += "}";

**Serial**.print("Sending payload: ");

**Serial**.println(payload);

if (client.publish(publishTopic, (char\*) payload.c\_str())) {

**Serial**.println("Publish ok");

} else {

**Serial**.println("Publish failed");

}

}

void mqttconnect() {

if (!client.connected()) { **Serial**.print("Reconnecting client to "); **Serial**.println(server);

while (!!!client.connect(clientId, authMethod, token)) {

**Serial**.print("."); delay(500);

}

initManagedDevice();

**Serial**.println();

}

}

void wificonnect()

{

**Serial**.println(); **Serial**.print("Connecting to "); WiFi.begin("Wokwi-GUEST", "", 6);

while (WiFi.status() != WL\_CONNECTED) { delay(500);

**Serial**.print(".");

}

**Serial**.println(""); **Serial**.println("WiFi connected"); **Serial**.println("IP address: "); **Serial**.println(WiFi.localIP());

}

void initManagedDevice() {

if (client.subscribe(subscribetopic)) {

**Serial**.println((subscribetopic));

**Serial**.println("subscribe to cmd OK");

} else {

**Serial**.println("subscribe to cmd FAILED");

}

}

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength)

{

**Serial**.print("callback invoked for topic: ");

**Serial**.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) {

//Serial.print((char)payload[i]); data3 += (char)payload[i];

}

**Serial**.println("data: "+ data3); data3="";

}

# Wokwi Link :

https://wokwi.com/projects/347021585567187540

# Output and Simulation :

# 

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

